

## **Introduction to Industrial Controls Using PLCs – Complete Outline**

1. Introduction to control systems – Definition and Types
2. Numbering system
  - a. Decimal
  - b. Binary
  - c. Octal
  - d. Hexadecimal
3. Logic and truth tables
  - a. AND
  - b. OR
  - c. NOT
4. Control System Components
  - a. Hardware components
    - i. Input devices (Switches, sensors, barcode readers, scanners...)
    - ii. Output devices (Pilot lights, Motors, etc.)
    - iii. PLCs – Types and Capabilities
    - iv. Communication (Ethernet, RS – 232)
  - b. Software components
    - i. Communication Software – RSLinx
    - ii. Programming Languages – Types and Applications
    - iii. HMI software – RSView32, Visual Basic

5. Allen Bradley PLCs
  - a. PLC Types and capabilities
  - b. SLC-500 Hardware Components
    1. Chassis
    2. Power supply
    3. Processor
    4. Input/Output cards
    5. Communication cable
  
6. Process of writing and executing ladder logic programs:
  
7. Introduction to ladder logic programming
  
8. Introduction to RSLogix500 software components
  
9. Addressing schemes for SLC 500
  
- 10.Ladder logic instruction set
  - a. Basic ladder logic instructions – XIO, XIC, OTE, OTL, OTU, etc
  - b. Internal relays
  - c. Timers and counters
  - d. Compare
  - e. Data handling
  - f. Subroutine
  
- 11.Editing, downloading and running ladder logic programs
  - a. Inserting, deleting, and changing instructions in a rung
  - b. Instruction mnemonics
  - c. Downloading programs

## 12.Ladder logic program debugging

- a. Forcing Inputs/Outputs
- b. Stepping through ladder logic program
- c. Identifying compile time errors
- d. Using RSLogix500 Help

## 13.Ladder logic program documentation

- a. Symbols
- b. Instruction comments
- c. Rung comments